Autonics

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- Δ symbol indicates caution due to special circumstances in which hazards may occur.
- Warning Failure to follow instructions may result in serious injury or death

Safety Considerations

Independent Single Display PID Temperature Controllers



TR1D Series

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- · Compact, space-saving design with 22.5 mm width size
- 50 ms high-speed sampling and \pm 0.3% display accuracy
- Simultaneous heating/cooling and automatic/manual control function
- · Switch between current output and SSR drive output
- Easy mount on DIN rails (patent)*1
- RS485 communication output model available
- Protocol: Modbus RTU or ASCII
- Communication speed: up to 115,200 bps
- Parameter setting via PC (USB or RS485 communication)
- Comprehensive device management software (DAQMaster) provided
- · Heater disconnect alarm function (CT input)
- Current transformer (CT) sold separately: CSTC-E80LN, CSTC-E200LN, CSTS-E80PP Screen protection function
- *1 Korea Patent Registration 10-2019-0158569, Korea Design Registration 30-1065663, China Design Registration 202030164351.2

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install the unit on DIN rail to use.** Failure to follow this instruction may result in electric shock.
- Failure to follow this instruction may result in electric shock.
 Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. **05. Check 'Connections' before wiring.**
- Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.**
 - Failure to follow this instruction may result in fire or electric shock.

Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m. When connecting the sensor input and communication cable without

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m. Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage **03. Use a dry cloth to clean the unit, and do not use water or organic solvent.** Failure to follow this instruction may result in fire or electric shock.
- Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.

- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- After changing the input sensor, moonly the value of the corresponding parameter.
 Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of
- external noise. • Make a required space around the unit for radiation of heat. For accurate temperature
- measurement, warm up the unit over 20 min after turning on the power.Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

Model	Control output1	Control output2	Option output	Additional function
TR1D-14RN ⁰¹⁾	Relay	-	-	-
TR1D-14RR	Relay	Relay ↔ Alarm	-	CT input, Dual alarm output ⁰²⁾
TR1D-R4RR	Relay	Relay ↔ Alarm	Transmission	CT input, Dual alarm output ⁰²⁾
TR1D-T4RR	Relay	Relay ↔ Alarm	Communication	CT input, Dual alarm output ⁰²⁾
TR1D-14CN 01)	Current/SSR	-	-	-
TR1D-14CC	TR1D-14CC Current/SSR		-	CT input
TR1D-R4CC	R4CC Current/SSR Curren Transn		Transmission	CT input, Dual transmission output
TR1D-T4CC	Current/SSR	Current/SSR ↔ Transmission	Communication	CT input

01) The model does not support terminal for the control output 2 is not available to use heating&cooling control and alarm outputs at the same time.

02) It is not possible to use dual alarm output and heating&cooling control at the same time.

Product Components

• Product

Instruction manual

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Unit Descriptions

Top termina block 1 to 4 5 to 8 01 02 . ♥ ⊘ 03 © 0 Bottom s, terminal block 13 to 9 to 12 04 05

RUN mode: Parameter:	play part (Red) Displays PV (Present value) and SV (Setting value). Displays name and setting value of parameters.					
Indicator	ON contition					
SV	SV display					
OUT	Control output□ ON					
AL1	AL1 alarm output ON					
	The difference between PV and SV is less than 2°C					
▲/▼	The difference between PV and SV is greater than 2°C					
°C or °F	'2-2 Temperature unit' parameter setting					
03. Control ke [M]: MODE [◀] / [▲] / 04. PC loader	key [▼]: Setting value control key					
	4. PC loader port Communication converter (Sold					

Use to mount and detach the DIN rail.

separately) connection **05. Bracket handle**

opee	incations					
Series		TR1D Series				
Power su	ipply	100 - 240 VAC~ 50/60 Hz				
Allowabl	e voltage range	90 to 110% of rated voltage				
	onsumption	≤ 8 VA				
Samplin	g period	50, 100, 250 ms				
	ecification	Refer to 'Input Type and Using Range'.				
Option input CT input		 0.0-50.0 A (primary current measurement range) CT ratio: 1/1,000, Measurement accuracy: ±5% F.S. ±1digit 				
	relay	250 VAC~ 3 A 1a				
Control output	SSR	$12 \text{ VDC} = \pm 3 \text{ V}, \le 20 \text{ mA}$				
output	Current	DC 4-20 mA or DC 0-20 mA (parameter), Load: \leq 500 Ω				
	Alarm	AL1, AL2: 250 VAC~ 3 A 1a				
Option output	Transmission	DC4-20 mA (Load resistance: \leq 500 Ω , Output accuracy: \pm 0.3% F.S.)				
	RS485 comm.	Modbus RTU / ASCII				
Display t		7 segment (red), 4-digit				
Control t	ype	ON/OFF, P, PI, PD, PID Control				
Hysteres		Control output: 1 to 100 °C/°F (0.1 to 100.0 °C/°F) Alarm output: 1 to 100 °C/°F (0.1 to 50.0 °C/°F)				
Proporti	onal band (P)	0.1 to 999.9 °C				
Integral	time (I)	0 to 9,999 sec				
Derivativ	ve time (D)	0 to 9,999 sec				
Control o	cycle (T)	Relay output: 0.5 to 120.0 sec, SSR drive output: 0.5 to 120.0 sec				
Manual r	eset	0.0 to 100.0%				
Dielectri	c strength	Between the power part and the case: 3,000 VAC $\sim 50/60$ Hz for 1 min				
Vibration	ı	0.75 mm amplitude at frequency of 5 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				
Relay life	Mechanical	OUT1/2, AL1/2: ≥ 5,000,000 operations				
cycle	Electrical	OUT1/2, AL1/2: \geq 100,000 operations (resistance load: 250 VAC \sim 5 A)				
Insulatio	n resistance	\geq 100 M Ω (500 VDC== megger)				
Insulatio	n type	Double insulation or reinforced insulation (dielectric strength between the power part and the case: 3 kV)				
Noise im	munity	Square shaped noise (pulse width: 1μ s) by noise simulator $\pm 2 $ kV R-phase, S-phase				
Memory	retention	pprox 10 years (non-volatile semiconductor memory type)				
Ambient	temperature	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)				
Ambient	humidity	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)				
Approva	l	(€				
Unit wei	ght (packaged)	≈ 123.5 g (≈ 194.5 g)				

Communication Interface

RS485

Specifications

K34 65			
Communication protocol	Modbus RTU / ASCII		
Application standard	EIA RS485 compliance with		
Maximum connection	31 units (address: 01 to 127)		
Synchronous method Asynchronous			
Communication method	Two-wire half duplex		
Communication effective range	≤ 800 m		
Communication speed	4,800 - 9,600 (default) - 19,200 - 38,400 - 57,600 - 115,200 bps (parameter)		
Response time	5 to 99 ms (default: 20 ms)		
Start bit	1 bit (fixed)		
Data bit	8 bit (fixed)		
Parity bit	None (default), Odd, Even		
Stop bit	1 bit, 2 bit (default)		

It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.

Input Type and Using Range

• The setting range of some parameters is limited when using the decimal point display.

Input typ	Input type		Display Method	Using range(°C)	Using range(°F)
	K (CA)	1	E C A'H	-50 to 1,200	-58 to 2,192
	K (CA)	0.1	E C A.L	-50.0 to 999.9	-58.0 to 999.9
	J (IC)	1	JI [.H	-30 to 800	-22 to 1,472
	J (IC)	0.1	J I E.L	-30.0 to 800.0	-22.0 to 999.9
Thermo	L (IC)	1	LIE.H	-40 to 800	-40 to 1,472
-couple	L (IC)	0.1	LIE.L	-40.0 to 800.0	-40.0 to 999.9
	T (CC)	1	Е С С.Н	-50 to 400	-58 to 752
		0.1	E C C.L	-50.0 to 400.0	-58.0 to 752.0
	R (PR)	1	r P r	0 to 1,700	32 to 3,092
	S (PR)	1	SPr	0 to 1,700	32 to 3,092
	DPt100Ω	1	d P E.H	-100 to 400	-148 to 752
	DPLIOUI	0.1	d P E.L	-100.0 to 400.0	-148.0 to 752.0
RTD	CU50 Ω	1	C U 5.H	-50 to 200	-58 to 392
	0000	0.1	C U 5.L	-50.0 to 200.0	-58.0 to 392.0
	Nickel120 Ω	1	n1 12	-80 to 260	-112 to 500

Display accuracy

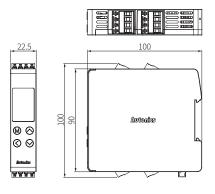
• The setting range of some parameters is limited when using the decimal point display.

Input type	Using temperature	Measurement accuracy
Thermocouple RTD	At room temperature (23°C±5°C)	$\begin{array}{l} (\text{PV}\pm0.3\% \text{ or}\pm1\ ^{\circ}\text{C} \ \text{higher one})\pm1\text{-digit}\\ \bullet \text{Thermocouple } (\text{PR}), S (\text{PR}) \ \text{below 200\ }^{\circ}\text{C}:\\ (\text{PV}\pm0.5\% \text{ or}\pm3\ ^{\circ}\text{C} \ \text{higher one})\pm1\text{-digit},\\ \text{Over 200\ }^{\circ}\text{C}:\\ (\text{PV}\pm0.5\% \text{ or}\pm2\ ^{\circ}\text{C} \ \text{higher one})\pm1\text{-digit},\\ \bullet \text{Thermocouple L} ((\text{C}), \text{RTD } \text{CuSO}\ \Omega:\\ (\text{PV}\pm0.5\% \text{ or}\pm2\ ^{\circ}\text{C} \ \text{higher one})\pm1\text{-digit}\end{array}$
	Out of room temperature range	$\begin{array}{l} (\text{PV}\pm0.5\% \text{ or}\pm2\ ^{\circ}\text{C} \text{ higher one})\pm1\text{-digit}\\ \cdot\text{Thermocouple }R(\text{PR}), S(\text{PR});\\ (\pm1.0\% \text{ or}\pm5\ ^{\circ}\text{C} \text{ higher one})\pm1\text{-digit}\\ \cdot\text{Thermocouple }L((C),\text{RTD Cu50}\ \Omega;\\ (\text{PV}\pm0.5\% \text{ or}\pm3\ ^{\circ}\text{C} \text{ higher one})\pm1\text{-digit}\\ \end{array}$

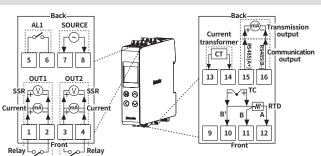
• When multiple products (or more) are mounted without separation, ±1°C is added to all accuracy.

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Connections

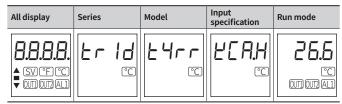


Terminal support by model

Terminal No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Function Model	Con out	trol put 1	Con out	trol out 2		rm tput	Po	wer	-			ature nput	CT inp	ut	Opt out	
TR1D-14RN	Rela	У	-		Rel	ay	0		-	TC RTD)	-	-	-	-	-
TR1D-14RR	Rela	У	Rela	y	Rel	ay	0		-	TC RTD)	-	0		-	-
TR1D-R4RR	Rela	У	Rela	y	Rel	ay	0		-	TC RTD)	-	0		Tran -mis	
TR1D-T4RR	Rela	у	Rela	y	Rel	ay	0		-	TC RTD)	-	0		Com -catio	imuni on
TR1D-14CN	Curr SSR		-		Rel	ay	0		-	TC RTD)	-	-	-	-	-
TR1D-14CC	Curr SSR	ent	Curr SSR	ent	Rel	ay	0		-	TC RTD)	-	0		-	-
TR1D-R4CC	Curr SSR		Curr SSR	ent	Rel	ay	0		-	TC RTD)	-	0		Tran -mis	
TR1D-T4CC	Curr SSR	ent	Curr SSR	ent	Rel	ay	0		-	TC RTD		-	0		Com -catio	imuni on

Initial Display When Power is ON

When power is supplied, after all display will flash for a while, series and model name are displayed sequentially. After input sensor type will flash twice, enter into RUN mode.



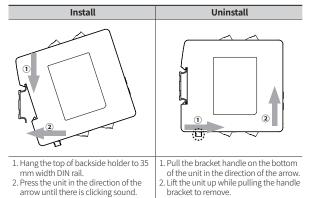
Errors

Display	Description	Troubleshooting
oPEn	Flashes if input sensor is disconnected or sensor is not connected.	Check input sensor status.
нннн	Flashes when PV is higher than input range.	When input is within the rated
LLLL	Flashes when PV is lower than input range.	temperature range, this display disappears.

Installation Method

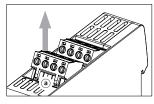
Mounting on DIN rail

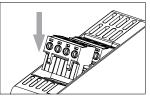
• Mount the metal part with a spanner so that a large force is not applied to the body.



Attaching and Dettaching a Terminal Unit

Detaching





Attaching

Lift the lower part of the terminal unit (a) upwards by using a tool (e.g. flat-head driver).

Press the terminal unit downwards to insert.

• When disconnecting terminal unit and wiring, refer to 'Connections' to attach to right position. Failure to follow this instruction may result in fire product damage or malfunction.

Mode Setting

	[▲] key over 2 sec	\rightarrow	Display part switching	Auto	\rightarrow	
	No key input over screen protection time	\rightarrow	Screen protection	[MODE], [◀], [▲], [▼] key	\rightarrow	
RUN	[▼] + [▲] key over 3 sec	\rightarrow	Digital input key	Auto	\rightarrow	RUN
	[MODE], [◀], [▲] or [▼] key	\rightarrow	SV setting	[MODE] key or no key input over 3 sec	\rightarrow	
	[MODE] key over 2 sec	\rightarrow	Parameter group	[MODE] key over 2 sec	\rightarrow	
	$[\blacktriangleleft] + [\blacktriangle] + [\blacktriangledown]$ key over 3 sec	\rightarrow	Parameter reset	Auto	\rightarrow	

Parameter Setting

- · Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the descriptions of each item.
- Select group by $[\blacktriangle], [\blacktriangledown]$ key and press [MODE] key to parameter setting mode in parameter group setting mode.
- [MODE] key: Move to next item after saving / Return to upper level with save (\geq 2 sec) $[\blacktriangleleft]$ key: Move digits / Return to the upper level without saving (\geq 2 sec) / Return to RUN mode without saving (\geq 3 sec)
- $[\blacktriangle], [\blacktriangledown]$ key: Select parameter / Change setting value
- Return to the upper level without saving when there is no key input for more than 30 seconds.
- The range in parentheses '()' is the setting range when the set value of the 'input specification' parameter is used with one decimal point.
- Recommended parameter setting sequence: Parameter 2 group \rightarrow Parameter 1 group → SV setting mode

Parameter 1 group

Para	ameter	Display	Default	Setting range	Condition	
1-1	Lock	Lo[Y	٥FF	OFF LOC1: Lock parameter 2 group LOC2: Lock parameter 1, 2 group LOC3: Lock parameter 1, 2 group + SV setting lock • It is possible to check the value only in lock mode.	-	
1-2	Heater current monitoring	C E - A	-	[CT input model] 0.0 to 50.0 A	2-10/11 Control output 1/2: SSR	
1-3	Auto tuning	ЯĿ	οFF	OFF, ON: Execution	2-9 Control type: PID	
1-4	AL1 alarm temperature	AL I	1250	Deviation alarm: -F.S. to F.S. °C/°F Absolute value alarm: Within input specification • Changing the '2-16/19 AL1/2 alarm	2-16/19 AL1/2 alarm	
1-5	AL2 alarm temperature	AL 2	1250	operation' and '2-17/20 AL1/2 alarm option' will automatically reset the value to the maximum or minimum that will not be output.	operation: AM1 to AM6, HBA	
1-6	Heating proportional band	H - P	10	0.1 to 999.9 °C/°F	-	
1-7	Heating integral time	H - I	240	0 (OFF) to 9999 sec	-	
1-8	Heating derivative time	Н- А	49	0 (OFF) to 9999 sec	-	
1-9	Cooling proportional band	[- P	10	0.1 to 9999 °C/°F	-	
1-10	Cooling integral time	E - I	240	0 (OFF) to 9999 sec	-	
1-11	Cooling derivative time	C - d	49	0 (OFF) to 9999 sec	-	
1-12	Dead band ⁰¹⁾	dЪ	٥	-Proportional band to +Proportional band °C/°F	2-9 Control type: P.P, P.ON, ON.P	
				-999 to 999 (-199.9 to 999.9) °C/°F	2-9 Control type: ON.ON	
1-13	Manual reset	r E S E	50	0.0 to 100.0%	1-7/10 Heating/ Cooling integral time: 0	
1-14	Heating hysteresis	н.н у 5	5	1 to 100 (0.1 to 100.0) °C/°F	2-9 Control	
1-15	Heating OFF offset	H.o S E	٥	0 to 100 (0.0 to 100.0) °C/°F	type: ONOF	
1-16	Cooling hysteresis	С.НУ5	5	1 to 100 (0.1 to 100.0) °C/°F	2-8 Control output mode	
1-17	Cooling OFF	C.o 5 Ł	٥	0 to 100 (0.0 to 100.0) °C/°F	02)	

When set to the - value, the overlap band is formed based on SV, perform the heating and cooling control at the same time.

02) Parameter display following to the setting value of '2-8 Control output mode' HEAT: '1-14 & 15 Heating hysteresis & OFF offset' COOL: '1-16 & 17 Cooling hysteresis & OFF offset' H-C: '1-14 & 15 Heating hysteresis & OFF offset', '1-16 & 17 Cooling hysteresis & OFF offset'

	Parameter 2	group)		
	meter	Display		Setting range	Condition
2-1	Input specification	In-E		Refer to 'Input Type and Using Range'	-
2-2	Temperature unit	Unit SPL.t		°C, °F	-
2-3 2-4	Sampling period Input correction	1 n-b		50, 100, 250 ms -999 to 999 (-199.9 to 999.9) °C/°F	-
2-5	Input digital filter	- 7 A u.F		0.1 to 120.0 sec	-
2-6	SV low limit value	L-5u		Within 2-1 Input specification	-
2-7	SV high limit value	H-5u	1200	L-SV \leq H-SV - 1-digit °C/°F	-
	Control output			H-SV ≥ L-SV + 1-digit °C/°F HEAT: Heating, COOL: Cooling, H-C:	
2-8	mode	o-FE	н-с	Heating&Cooling	-
2-9	Control type	[-ād	P.P	PID, ONOF: ON/OFF, P.P: PID-PID*, ON.ON: ON/OFF-ON/OFF*, P.ON: PID-ON/OFF*, ON.P: ON/OFF-PID*	* 2-8 Control output mode: H-C
2-10		oUEI	CUrr	[Current/SSR output model]	-
	Control output 2 Control output 1	0055		SSR, CURR: Current	
2-12	range	0 l.ñA	4.30	4-20, 0-20 mA	2-10/11 Control output 1/2:
2-13	Control output 2	o 2.ñ R	1.50	4-20, 0-20 MA	CURR
	range			[Relay output model]	-
	Heating control		2 0.0	0.5 to 120.0 sec	-
2-14	cycle	H-E	2.0	[Current/SSR output model]	2-10/11 Control
			L.U	0.5 to 120.0 sec	output 1/2: SSR
	Cooling control		2 0.0	[Relay output model] 0.5 to 120.0 sec	-
2-15	cycle	[[-E		[Current/SSR output model]	2-10/11 Control
	,		2.0	0.5 to 120.0 sec	output 1/2: SSR
2-16	AL1 alarm operation	AL - 1	8ō L8 □□□.■	AM0: OFF AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low limit reserve alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm LBA: Leater break alarm	-
2-17	AL1 alarm option			A: Standard alarm, B: Alarm latch, C: Standby sequence I, D: Alarm latch and sequence 1, E: Standby sequence 2, F: Alarm latch and sequence 2 Enter to option setting: Press [4] key in 2-16 AL-1 alarm operation.	-
2-18	AL1 Hysteresis	ค เหร	1	1 to 100 (0.1 to 50.0) °C/°F	2-16/17 AL1/2 Alarm operation: AM1 to AM6 or HBA
2-19	AL2 alarm			[Dual alarm output model]	2-8 Control
	operation	RL-2	คล เค	Same as '2-16/17 AL1 alarm operation/	output mode:
2-20	AL2 alarm option			option'	HEAT or COOL
2-21	AL2 hysteresis	R5'HA	1	[Dual alarm output model] 1 to 100 (0.1 to 50.0) °C/°F	2-16/17 AL1/2 Alarm operation: AM1
2-22	LBA time ⁰¹⁾	L L A.E	п	0 to 9999 sec or auto setting ⁰²⁾	to AM6 or HBA 2-16/17
			2	0 to 999 (0.0 to 999.9) °C/°F or Auto setting	
2-23	LBA band	L Ь Я.Ь	2	03)	operation: LBA
2-24	Transmission output1 mode	Ro.ñ I	Pu	[Transmission output model] PV, SV, H-MV: Heating MV), C-MV: Cooling MV	
2-25	Transmission	FSIL	- 5 0		-
	output1 low limit			[Transmission output model]	
2-26	Transmission output1 high limit	F S LH	1500	Refer to 'Input Type and Using Range'	
2-27	Transmission output2 mode	R o. ñ 2	Pu	[Dual transmission output model] PV, SV, H-MV: Heating MV, C-MV: Cooling MV	2-8 Control
2 20	Transmission	66.0			output mode:
2-28	output2 low limit	FSIL	- 50	[Dual transmission output model]	HEAT or COOL
2-29	Transmission output2 high limit	F S LH	1200	Refer to 'Input Type and Using Range'	
			c	STOP: Stop control output, ALRE: Alarm	
2-30	Digital input key	di - E	StoP	reset, AT: Auto tuning execution, OFF	-
2-31	Sensor error, MV	Er.ñu	٥	0.0 (OFF) to 100.0 (ON) -100 (Cooling ON) to 0.0 (OFF) to 100 (Heating ON)	2-8 Control output mode: HEAT or COOL 2-8 Control output mode: H-C
2-32	Screen protection	d S P	oFF	OFF, 1, 30, 60 min	-
2-33	Comm. protocol	PrEL	rtU	RTU: Modbus RTU, ASCI: Modbus ASCII	-
2-34		RdrS		1 to 99	-
2-35		6P5		48, 96, 192, 384, 576, 1152 (×100) bps	-
2-36 2-37	Comm. parity bit Comm. stop bit	Prty StP		None, Even, Odd 1, 2 bit	-
2-31		r 5 5.5		5 to 99 ms	-
2-39	Comm. write	Eoñy	E n.A	EN.A: Enable, DIS.A: Disable	-
2-40	Parameter reset	Init	n 0	YES, NO	-

2:40 Parameter reset: PTME1 TDTLS, RO [10] Its3, RO [10

02) After auto tuning, the range is set as twice of the integral time automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.
 03) After auto tuning, the range is set as 10% of the proportion band automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.

Function: Alarm

888.8 Alarm Alarm operation option

Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Name	Alarm operation		Description
-	-		No alarm output
Deviation high limit	OFF H ON SV 100°C 110°C High deviation: Set as 10°C	OFF ↓ H ↑ ON A PV SV 90°C 100°C High deviation: Set as -10°C	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.
Deviation low limit	ON H OFF PV SV 90°C 100°C Low deviation: Set as 10°C	If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON.	
Deviation high, low limit	ON TH O A PV S 90°C 100 High, Low devia	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.	
Deviation high, low limit reverse	A PV S 90°C 100	N H OFF A A V PV °C 110°C ation: Set as 10°C	If deviation between PV an SV as high/low-limit is lowe than set value of deviation temperature, the alarm output will be OFF.
Absolute value high limit	OFF H ON PV SV 90°C 100°C Absolute value: Set as 90°C	OFF H ON SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is higher than the absolute value, the output will be ON.
Absolute value low limit	ON H OFF PV SV 90°C 100°C Absolute value: Set as 90°C	ON H OFF	If PV is lower than the absolute value, the output will be ON.
Sensor break	-	It will be ON when it detect sensor disconnection.	
Heater break	-		It will be ON when it detect heater disconnection.
Loop break	-		It will be ON when it detect loop disconnection.

	Description Condition								
Name	Description	Condition of re-apply							
Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-							
Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-							
Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Damas ON							
Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second Lalarm condition, alarm latch operates.	Power ON							
Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm temperature							
Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	/ operation or change STOP to RUN mode							

Segment Table

7 Segment				11 Segment			12 Segment			16 Segment					
٥	0	1	1	۵	0	1	1	٥	0	1	1	۵	0	Ĩ	1
1	1	J	J	1	1	J	J	1	1	J	J	-1-	1	ΰ.	J
2	2	Ľ	К	2	2	ĸ	K	2	2	К	К	2	2	ĸ	K
Э	3	L	L	Э	3	L	L	Э	3	L	L	Э	3	L	L
Ч	4	ñ	М	Ч	4	Μ	М	Ч	4	Μ	М	Ч	4	М	М
5	5	n	Ν	5	5	N	Ν	5	5	N	N	5	5	N	Ν
6	6	ο	0	Б	6	٥	0	Б	6	٥	0	Б	6	۵	0
Л	7	Ρ	Р	7	7	Ρ	Р	7	7	Ρ	Р	7	7	Ρ	Р
8	8	9	Q	8	8	۵	Q	8	8	Q	Q	8	8	Q	Q
9	9	r	R	9	9	R	R	9	9	R	R	9	9	R	R
A	A	5	S	Я	Α	5	S	Я	Α	5	S	R	А	5	S
Ь	В	F	Т	Ь	В	F	Т	Ь	В	Ł	Т	3	В	Ţ	Т
C	С	U	U	٢	С	U	U	C	С	U	U	٢	С	U	U
Ь	D	U	V	Ь	D	V	V	d	D	V	V	D	D	V	V
Ε	E	Ļ	W	Ε	E	М	W	Ε	E	Ы	W	Ε	E	И	W
F	F	5	Х	F	F	×	X	F	F	×	X	F	F	×	X
G	G	Ч	Y	۵	G	Ч	Y	6	G	Ч	Y	6	G	Y	Y
Н	н	Ξ	Z	н	Н	Z	Z	Н	Н	Z	Z	н	Н	2	Z
	0 1 2 3 4 5 6 7 7 8 9 8 9 8 8 9 7 8 6 7 0 8 6 7 7 8 8 9 6 7 7 8 8 9 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	D O I 1 I 2 I 3 I 4 I 5 I 3 I 4 I 5 I 6 I 7 I 8 I 9 I A I 6 I 7 I 8 I 9 I A I A I A I A I A I A I A I A I A I A I A I A I A I A I A I A I B I A	0 0 1 1 1 J 2 2 K 3 3 L 4 4 5 5 5 n 5 5 n 6 6 0 7 7 P 8 8 9 9 9 r 8 8 9 9 9 r 8 8 9 9 9 r 8 8 9 9 9 r 8 8 9 9 7 r 8 8 9 9 7 r 8 8 9 9 7 r 8 8 9 9 1 1 1 1 1 1 1 1	D J I I J J I J J 2 L K 3 L L 4 n M 5 5 n N 5 6 o O 7 P P 8 8 9 Q 9 9 r R A 5 S S b B L T C C U U d D u V E E Y W F F N X G G Y Y	0 i i 0 1 1 J J i 2 2 2 K 2 3 1 L 3 4 7 M 4 5 5 n N 5 6 0 0 5 7 P P 7 8 9 Q 8 9 r R 9 A 5 S R b B E T b B E T c C U U C d D u V d E E Y W E F F S X F G G Y Y G	0 i I 0 0 i 1 J j i 1 2 2 2 K 2 2 3 L L 3 3 4 6 M 4 4 5 5 6 0 6 7 7 7 7 7 8 9 Q 8 8 9 7 R 9 9 A 5 S A A 5 6 0 0 6 6 7 7 7 7 7 7 8 8 9 Q 8 8 9 7 R 9 9 7 R 8 9 9 7 8 8 9 Q 8 8 9 7 R 8 9 9 8 1 U U C C	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	D i I D 0 i I D 0 i I D 0 i I D 0 i I D 0 i I D 0 i I D 0 i I D J I I J J I I J J I I J J I I J J I I J J I I J J I I J	0 i 1 0 i 1 0 0 i 1 0 0 i 1 1 1 J J i 1 J J i 1 J	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	0 i 1 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1	0 i 1 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 0 0 i 1 1 0 0 i 1 1 0 0 i 1 1 1 0 0 i 1 1 1 0 0 i 1 1 1 1 0 0 i 1 1 1 0 0 i 1 1 1 0 0 i 1 1 0 0 i 1 1 0 0 i 1 1 0 0 i 1 1 0 0 i 1 1 0 0 0 0 0 1 1 1 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0